



### Action from the First Meeting

Examine programmatic/implementation options of using common/multiple surface and orbiting platforms (e.g., multiple MSL & MTO) to achieve fiscal efficiency while being responsive to a vibrant science strategy.

Specifically address how MSR can capitalize on MSL investment to make MSR more affordable.

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#### Impetus for Today's Presentation

Early Results from the MSR Pre- Project

 Core Product Action Item from the Mars Roadmapping Committee

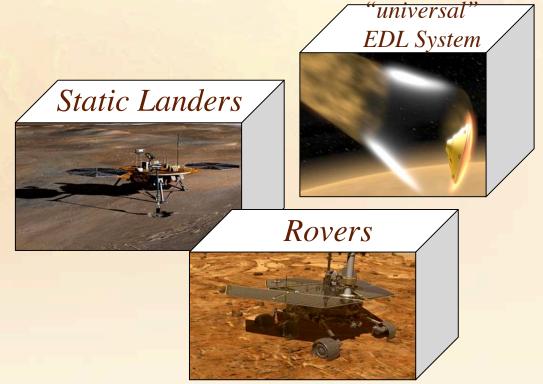
Today's Presentation



#### Missions Sequence — Built Out of Building Blocks

- Core products considered :
  - 1. A universal EDL
  - 2. MSL line of rovers
  - 3. Static Landers
  - 4. An orbiter platform MRO/MTO derivative





# Customer Missions for Core Products

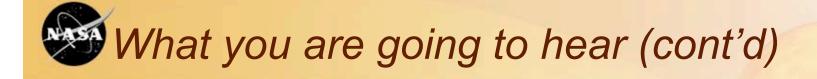
- Customers for core products are assumed to be :
  - The Core strategic missions
    - MSL,
    - MSR,
    - AFL,
    - Deep Drill,
    - Human Precursor Platforms,
    - MTO
  - But not Scouts
    - Too many possibilities
    - Last competition resulted in:
      - An orbiter
      - A lander
      - A airplane
      - Atmospheric sample return sample



- 1. Common Orbiters
- 2. Universal EDL
- 3. Common Static Landers
- 4. Common MSL-class Rovers
- 5. MSL/MSR Commonality
- 6. Potential Mission Scenarios

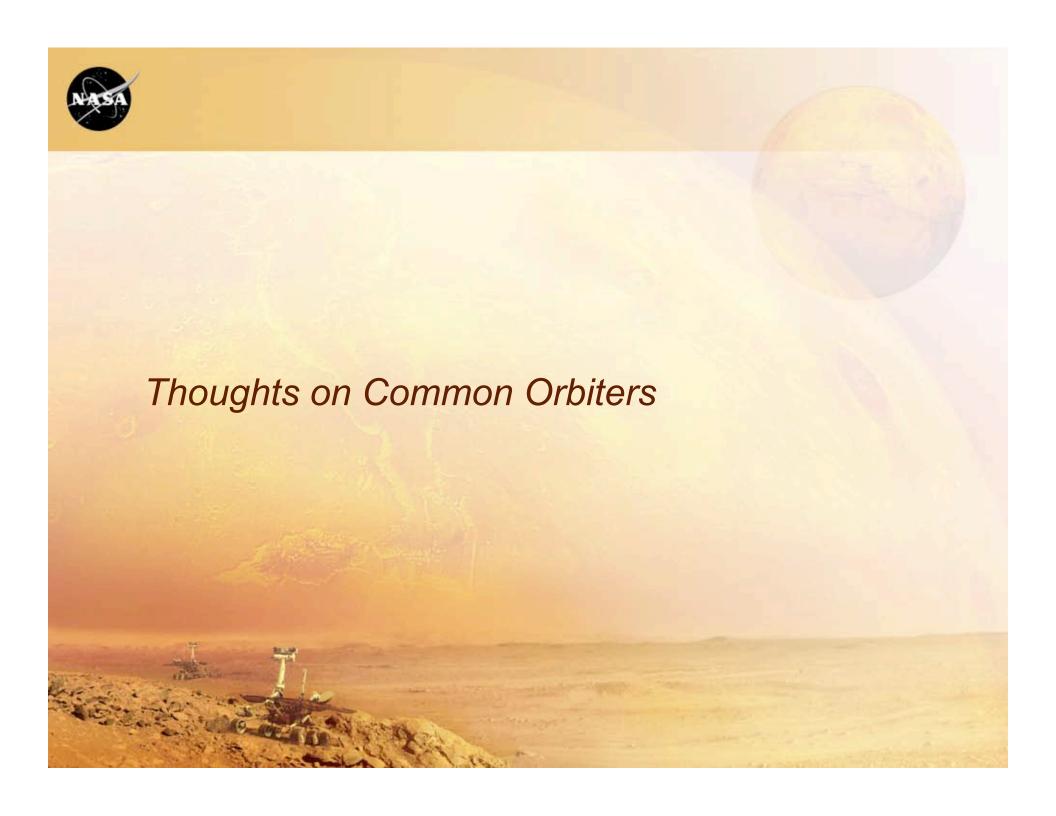
# What you are going to hear

- 1. Orbiters: a great deal of commonality possible
  - Issue: Desire to compete at every opportunity vs going to the the supplier with previous heritage
  - Infrequency of occurrence
- 2. Static Landers: A great deal of commonality possible
  - Same two issues as above
- 3. Rovers: Multiple copies of MSL
  - Issues: mass, planetary protection requirements, cost
- 4. EDL: Possibility for a universal EDL but we need to overcome several challenges
  - In MER (actual) and MSL (estimate) ~ 40% of the cost of the flight system is in EDL



#### Challenges of EDL

- We are now getting into applications that need to land up to 7 times more useful mass (compared to ~180kg of Spirit and Opportunity) on Mars
- Atmospheric challenges
- Altitude: we have only landed at -1Km or below so far
  - Want to land at higher altitudes with large mass
- With all of the above, we are well over the Viking heritage capability EDL
- But all is not lost





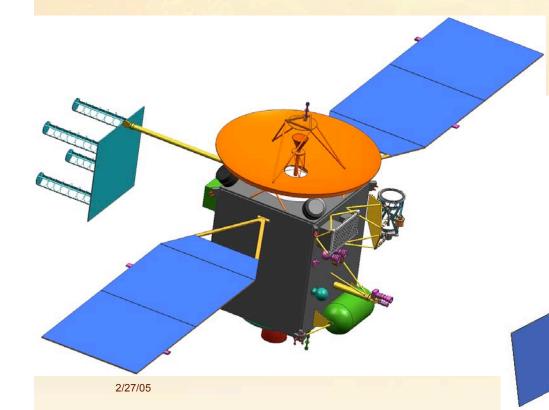
### Two Classes of Orbiter

#### Telecom S/C

- High Orbit (~ 4,000 km)
- Example MTO
- High gain antenna body fixed and Earth pointed

#### Science S/C

- Low Orbit (~ 400 km)
- Example MRO
- High gain antenna & S/A gimballed
- Science Instrument panel and Mars relay antenna nadir pointed





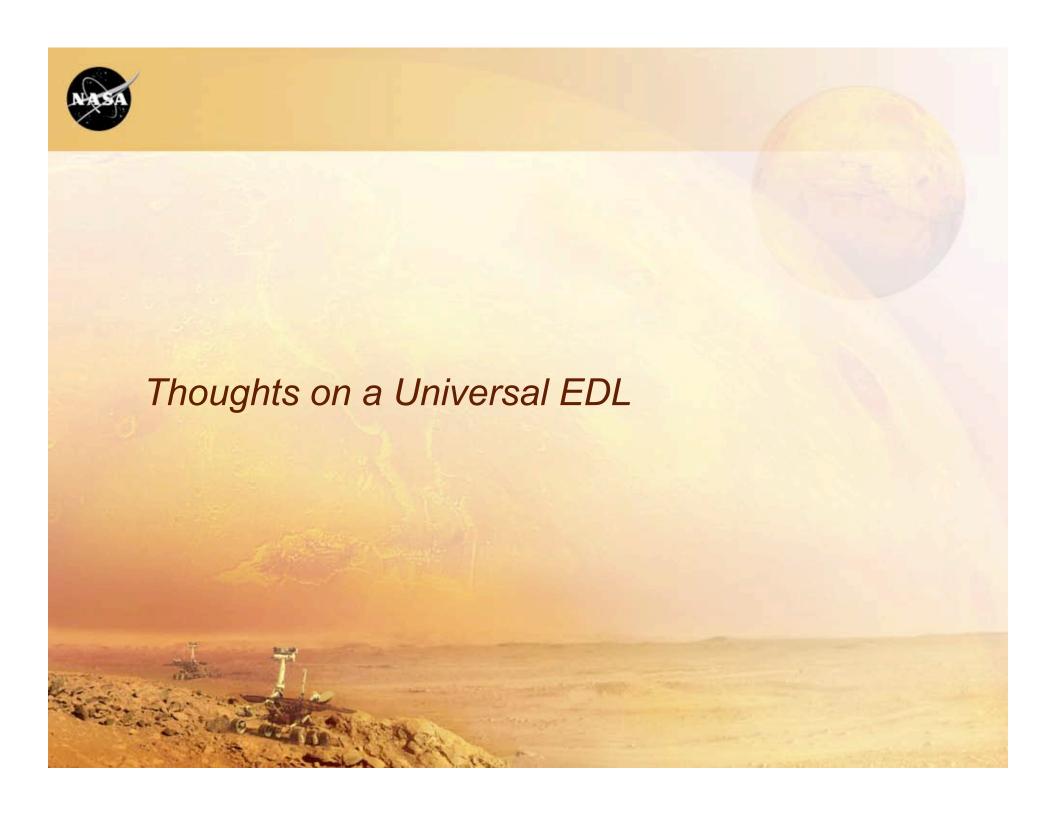
## Potential Applications

- Candidate Science Missions
  - Methane mapping orbiter
  - SAR mapping orbiter
- Candidate Telecom Missions
  - First MTO + technology demonstration of Laser Com, RAN
  - Second MTO + Scout Opportunity
    - 120 kg carried into high orbit or
    - 300 kg payload released prior to MOI
- MSR Orbiters

High degree of commonality at the subsystem level between all these orbiters possible

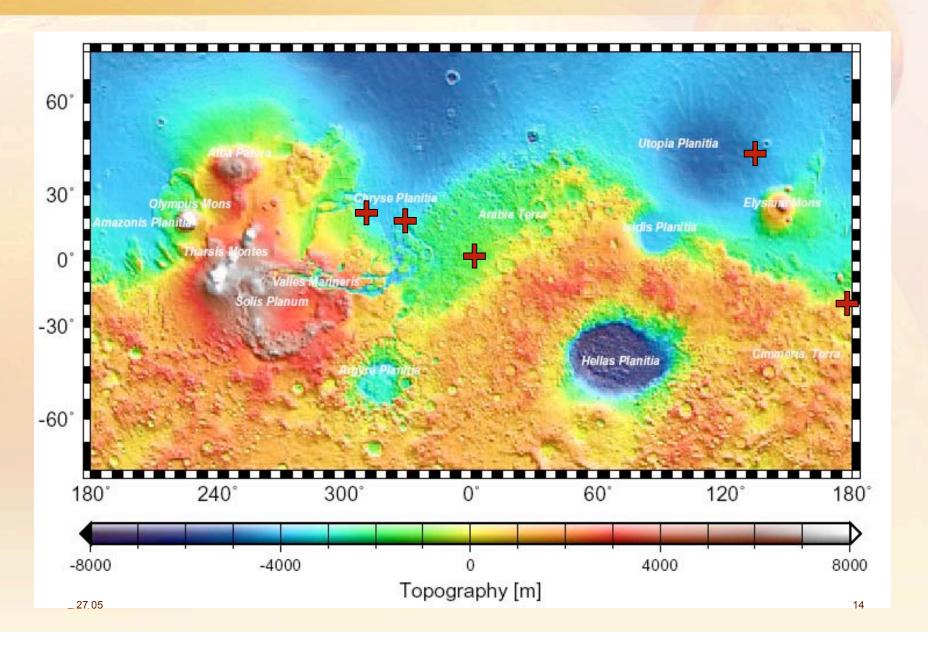


- In general use of a common platform gains fiscal savings but eliminates another desire of the NASA/OMB which is competition at every opportunity
- We used open competition RFP to solicit MTO
  - RFP released Fall 2004
  - Launch in 2009
- There is a current Mars science orbiter (MRO) wrapping up development for launch in August 2005
- It is inevitable that the MRO contractor would use commonality of subsystem to gain competitive advantage



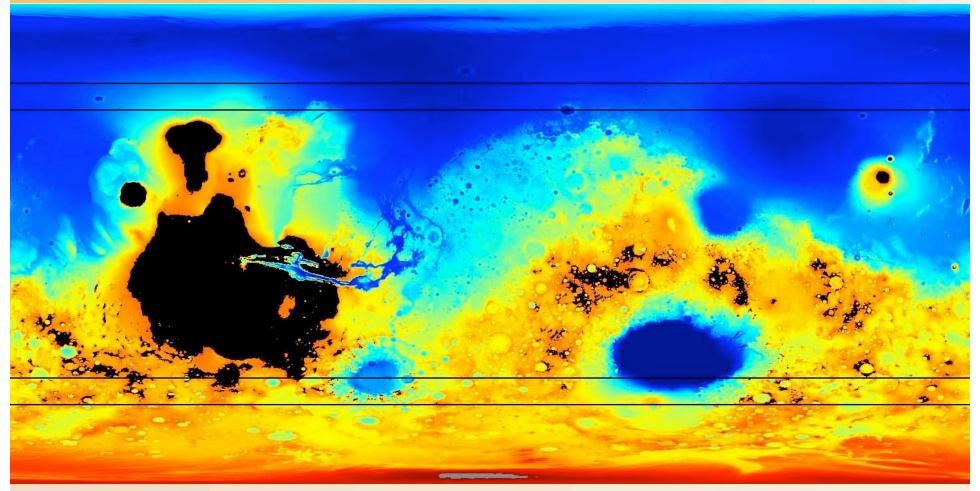


# Past Mars Landings





### Mars above 2.5 km in Black

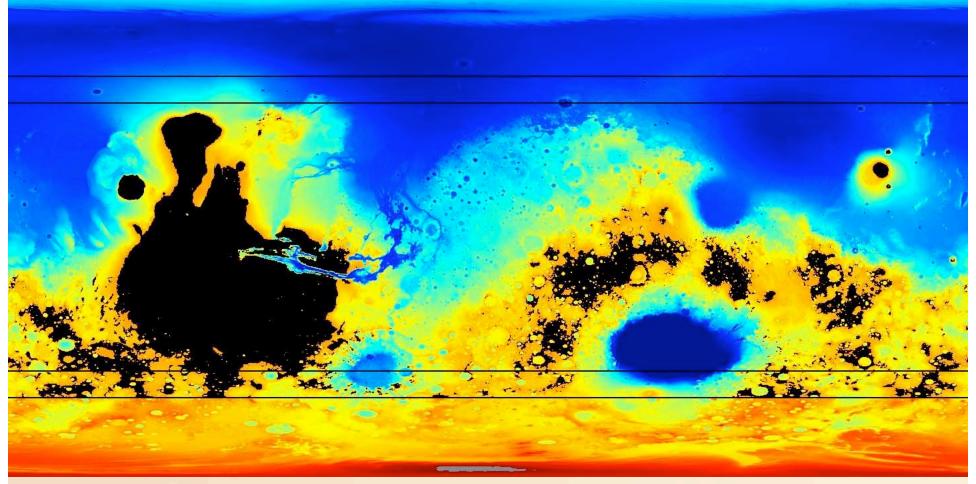


• Lines at ±50°, ±60° latitude

MOLA Topography ±90° Lat, 180° to -180°W Lon



# Mars above 2.0 km in Black

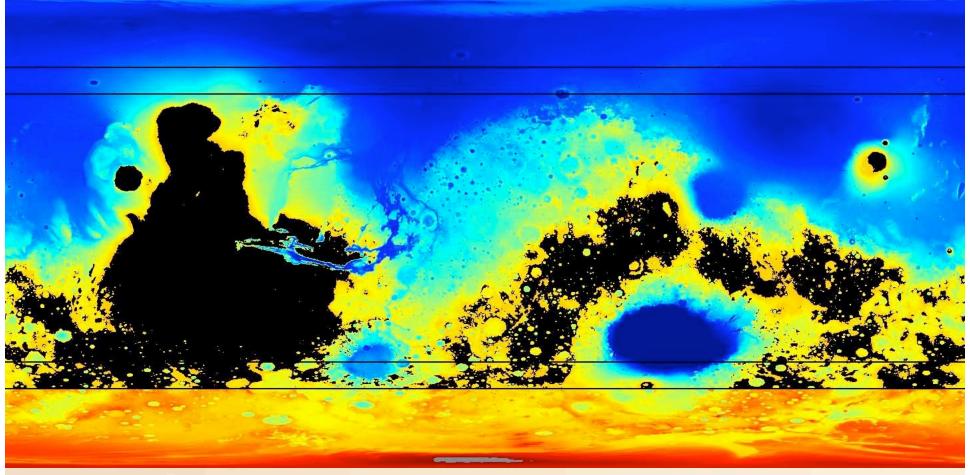


• Lines at ±50°, ±60° latitude

MOLA Topography ±90° Lat, 180° to -180°W Lon



## Mars above 1.5 km in Black

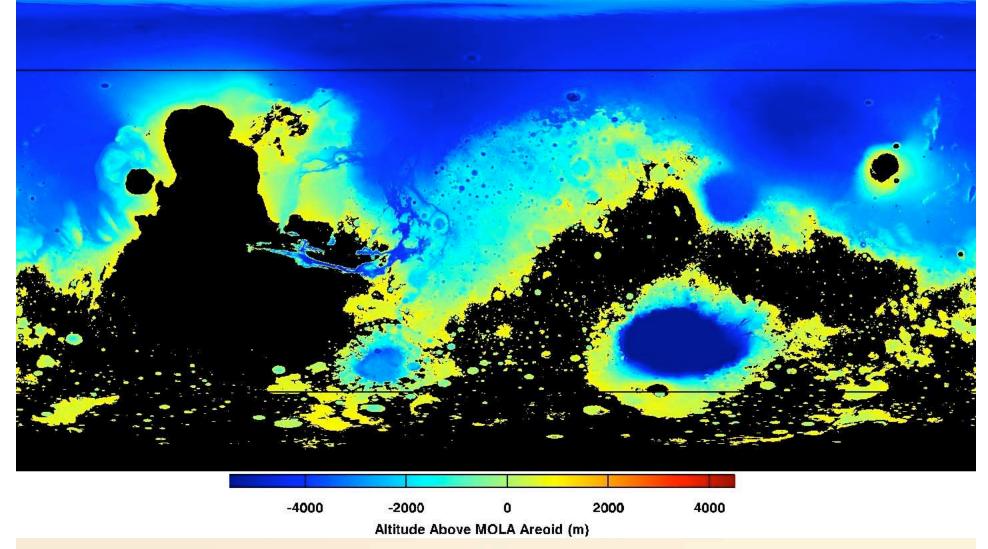


- Black area is topography > 1.5 km
- Lines at ±50°, ±60° latitude

MOLA Topography ±90° Lat, 180° to -180°W Lon



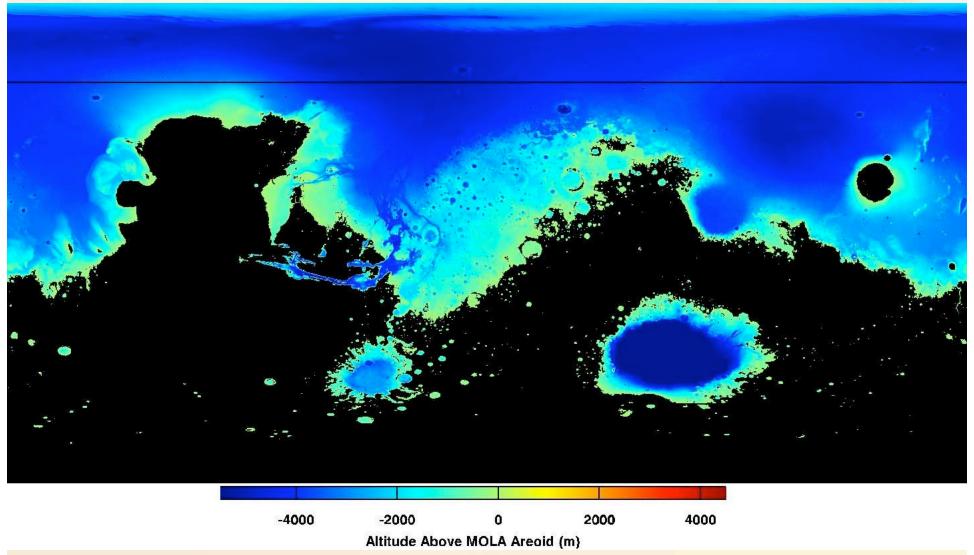
# Mars above 1.0 km in Black



Black area is topography > 1.0 km Lines/ats±60° latitude



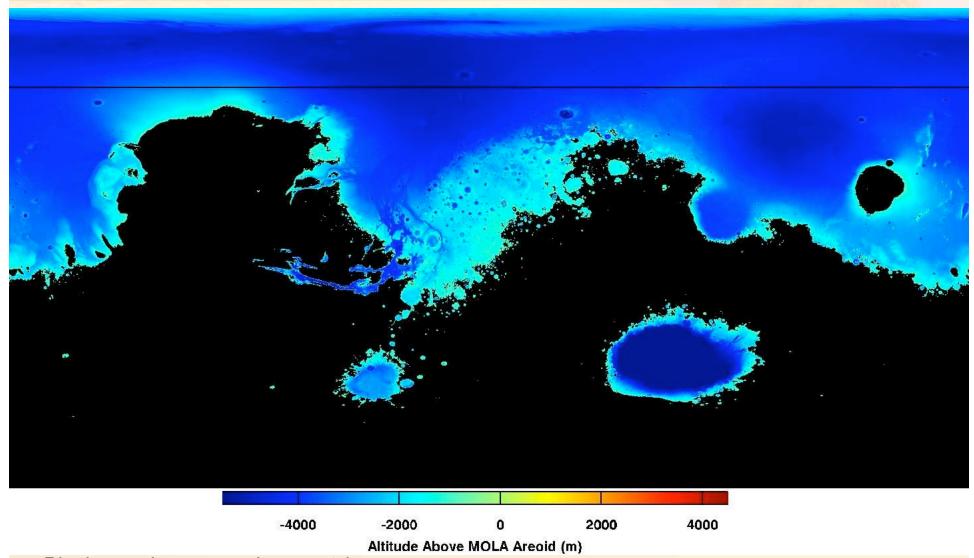
# Mars above 0 km in Black



Black area is topography > 0.0 km Lines/at5±60° latitude



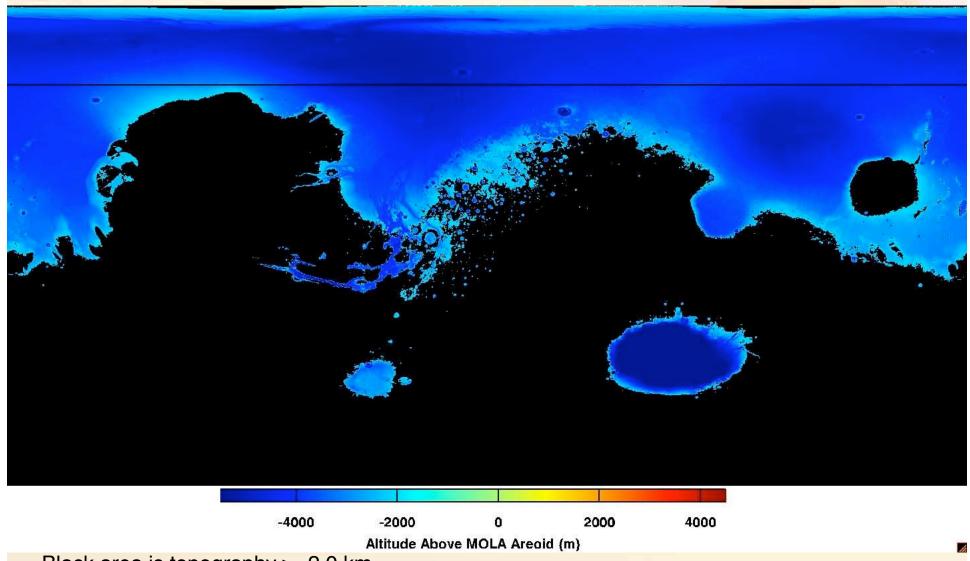
# Mars above -1.0 km in Black



Black area is topography > -1.0 km Lines/at ±60° latitude



# Mars above -2.0 km in Black

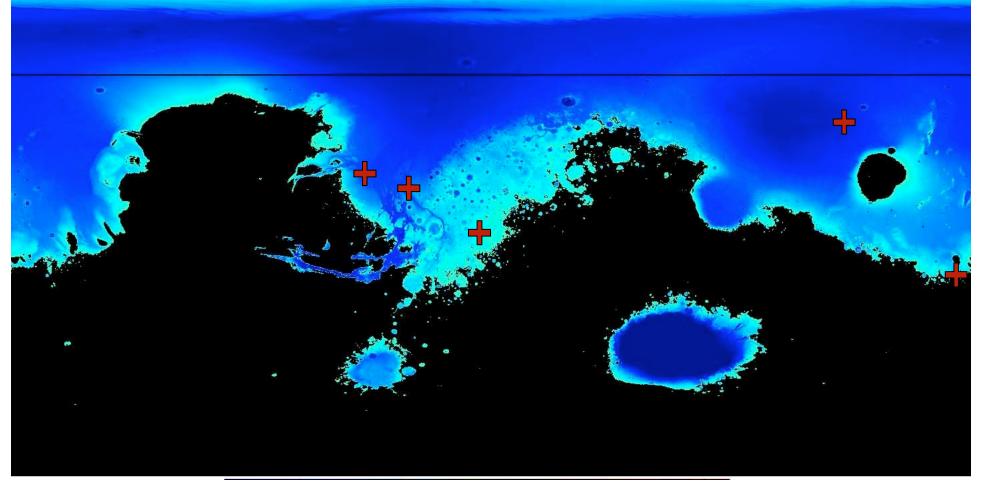


Black area is topography > -2.0 km Lines/at ±60° latitude

Note: Top of N. polar cap is shaded



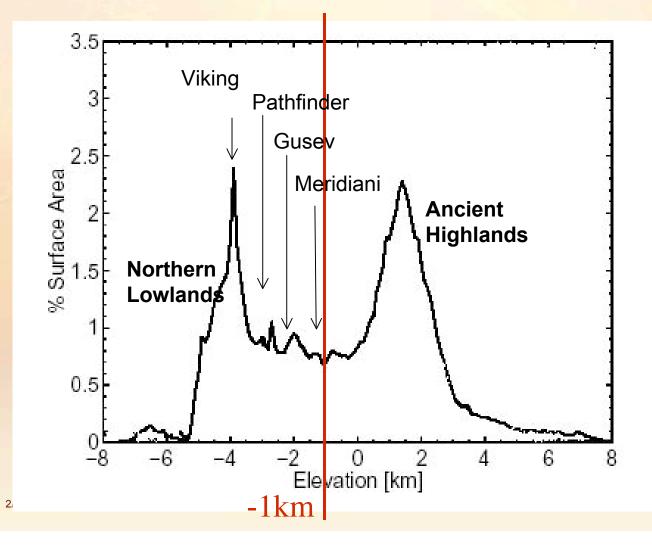
## Our Past Performance -- All below -1KM



- So far the highlands have been out of reach.
- What has stopped us from going higher?

# Elevation Variation

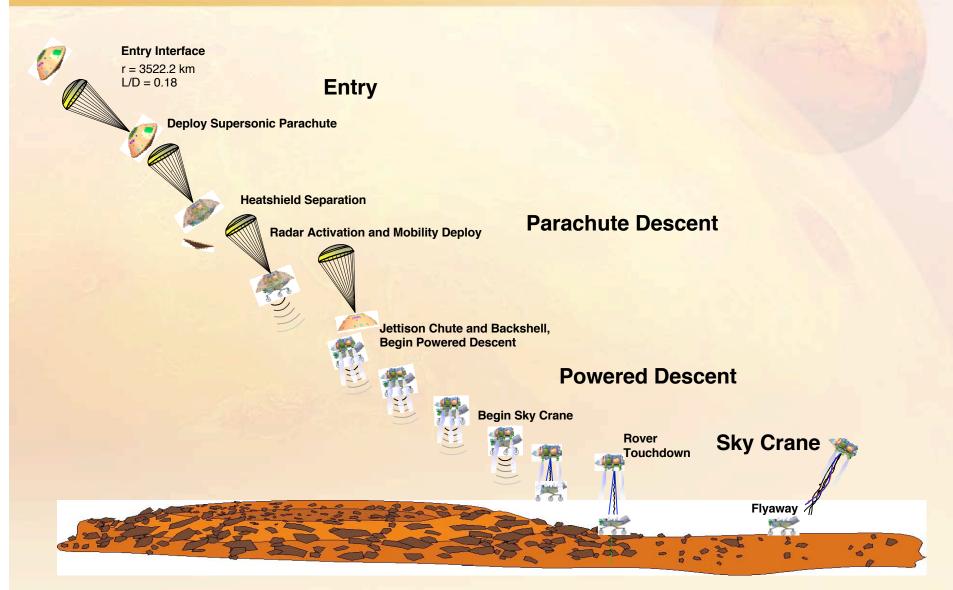
- The highest landing to-date is Opportunity at Meridiani @ -1 km MOLA.
- We are still 2 km below the flanks of the Highlands.



Topography has bimodal distribution



## Skycrane Architecture



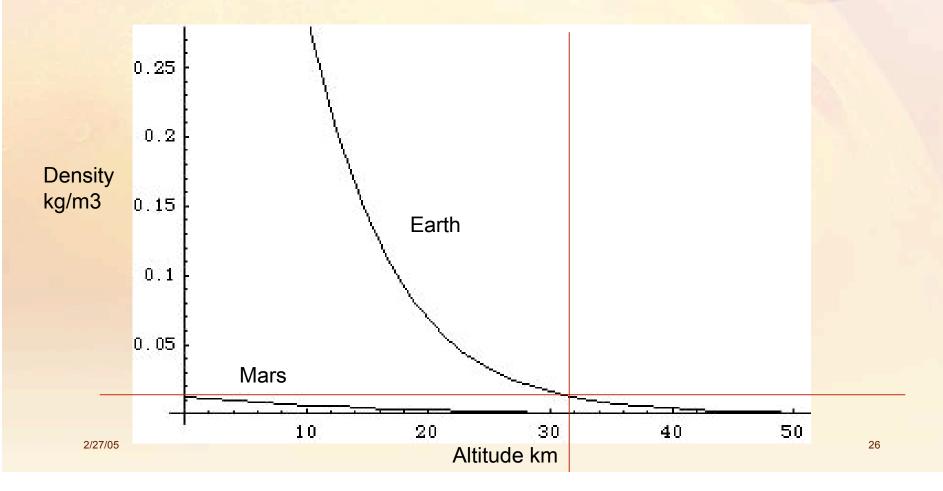


- Low density atmosphere
- Dust loading of the atmosphere (or "Tau")
- Seasonal atmospheric variation across opportunities



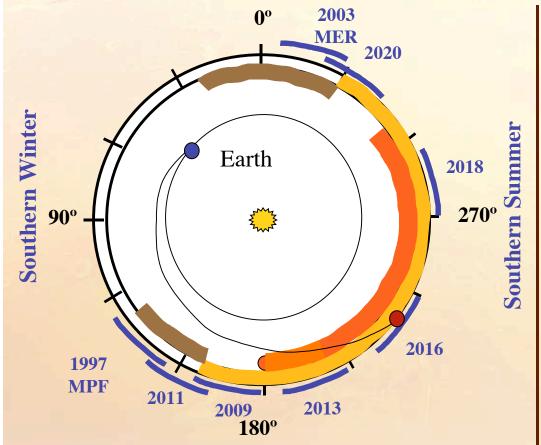
### Atmosphere Density

- Density = 1% of Earth's
- Surface atmosphere of Mars has the same density as the Earth atmosphere at ~ 30km
  - Imagine having to land the Shuttle at 100,000 ft!





### What we Know of Dust Storm on Mars

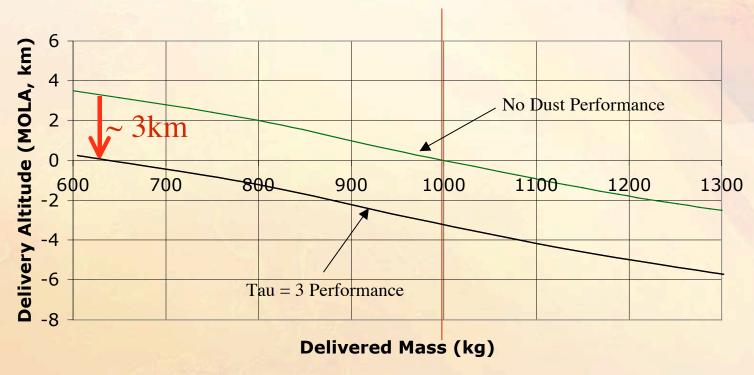


Yellow = Regional Dust Storms
Red = Planet-encircling Dust Storms
Brown = Regional Dust Storms did not occur
Local Dust Storms occur at all seasons

- Dust changes atmospheric density profile
- Roughly 1 in 3 probability of a global dust storm in any given year:
- τ is a measure of dust in atmosphere
  - τ = 3 is global average in a post storm season
  - $-\tau$  >7 has been observed



#### Effect of Dust in Delivered Mass vs Altitude



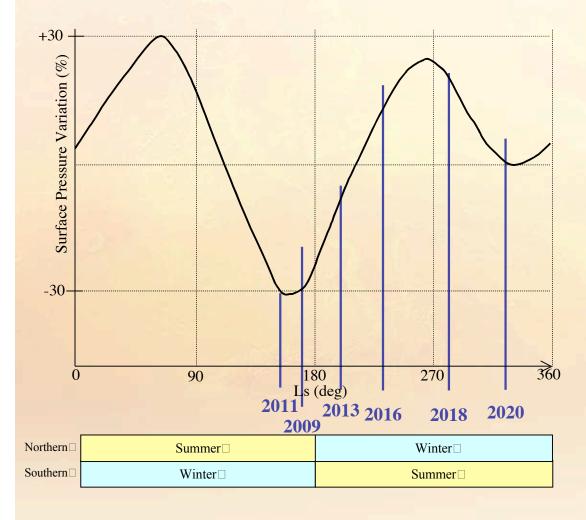
— Optimized EDL

#### **Assumptions**

- Performance for the 2013 opportunity
- Skycrane architecture, Descent Stage optimized for delivered mass
- Two parachute system used, Viking supersonic and 110 ft. subsonic
- Maximum aeroshell diameter used (5.0 m)



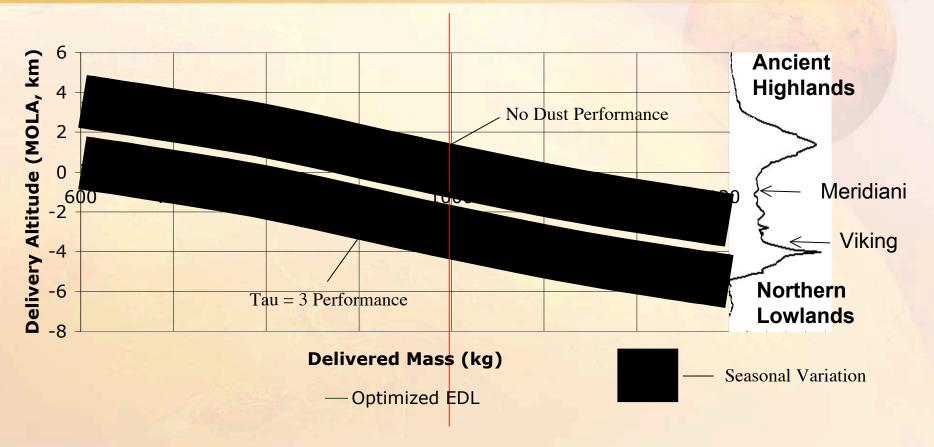
#### Seasonal impact on Delivered Mass vs Altitude



- Atmosphere Variation
  - The amount of air drops in the winter by 30% (moves to poles)



#### Effect of Seasonal variation on Delivered Mass vs Altitude



#### **Assumptions**

- Performance for the 2013 opportunity
- Skycrane architecture, Descent Stage optimized for delivered mass
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## Effect of Common Design on Lower Mass payloads

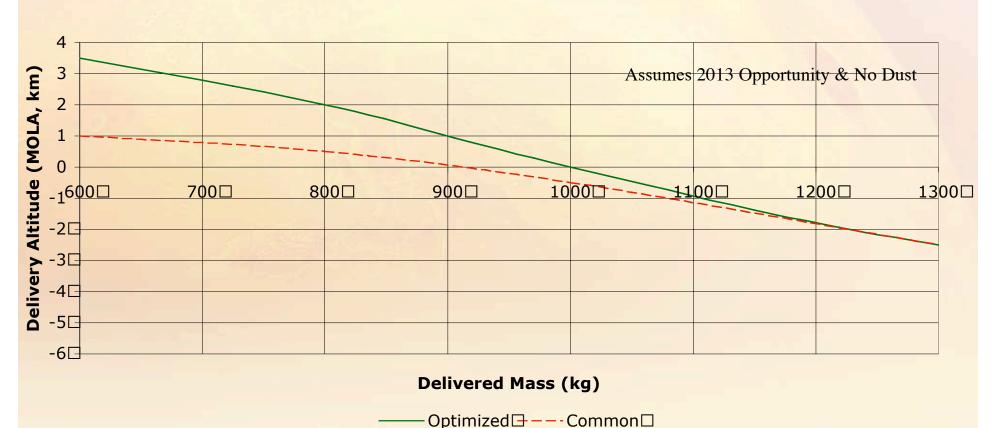
- If we were to develop a common EDL system design to encompass future missions mass delivery needs MSR would be the principal driver with ~1300 kg delivered mass
- Missions with lower delivered mass needs will lose altitude performance (compared to optimal design)



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### "Common" Landing System Impact

- Common EDL designed around 1300kg delivered mass
- For lower masses, this system is less efficient than optimal
- But for large delivered masses, efficiency loss is small compared to environmental factors



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### Milking the Viking Investment

# We are still living off the Viking technology investment of nearly 4 decades ago

- Entry Vehicle
  - 70 deg cone shape
  - Diameter driven by launch vehicle faring (5 m is largest available)
  - Lift to Drag Ratio as high as 0.24
- Supersonic Parachute Size
  - 16.15 m (53 feet) diameter is the largest qualified chute from Viking BLDT test program
- Parachute Opening conditions
  - Dynamic pressure limit as high as 800 Pascals
  - Mach 2.2

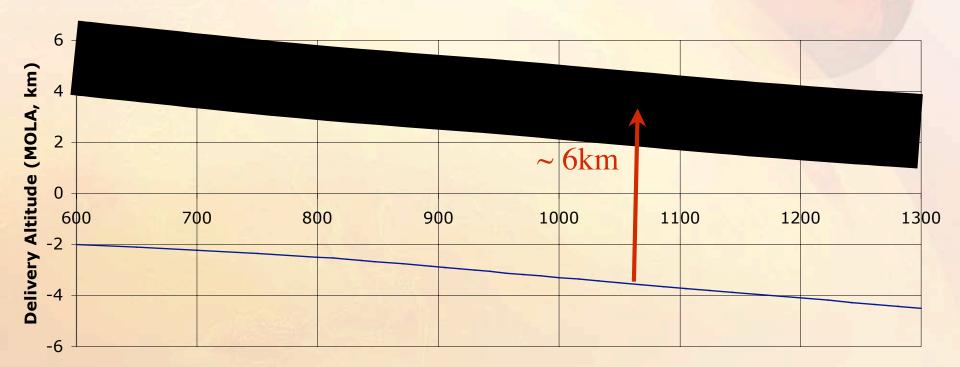
# Breaking out of the Viking Paradigm

- Next Generation Supersonic Parachute
  - Larger parachute deployable at higher Mach numbers
  - End-to-end simulation of EDL shows that the performance gains of 6km in altitude are possible
- Larger launch vehicle fairing and heatshield diameter
  - 6.5 m LV fairing would allow for ~6.0 m aero-shell
  - Performance gains of ~1-2km in altitude possible in conjunction with larger parachute
  - Unknown impact on launch vehicle cost & performance



#### Altitude Capability w/Improved Parachute

#### Improvement due to parachute



#### **Delivered Mass (kg)**

- Common EDL designed for 1300 kg delivery requirement
- Dust degraded performance assumed ( $\tau$  = 3.0)
- 2013 opportunity



#### **Orbital Entry Options**

- Given the uncertainty of the dust in the atmosphere one possibility is to go into orbit and "ride it out" a la Viking
- Orbit insertion options
  - Propulsive
  - Solar Electric Propulsion
  - Aerocapture

## Cost/Benefit Comparison Orbit insertion vs Parachute

#### Parachute

- Mitigates dust concern
- Significant non-recurring costs to develop parachute (~\$100M)
- Small NRE costs (~\$1M)
- Orbit Insertion
  - Fully mitigates dust concern
  - Increased launch vehicle costs (~\$100M per launch)
  - Increased cruise/insertion stage costs
  - Still need to develop new parachute to improve altitude capability

Parachute is a cost effective solution for increased altitude capability

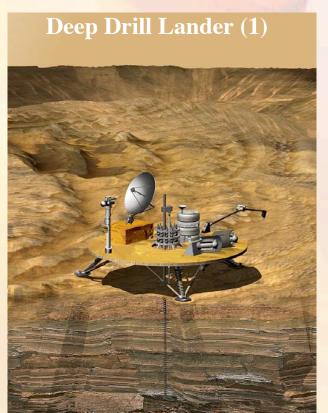


## Opportunities for Static Lander Applications

**Human Precursor Technology Test-beds (1-3)** 







Mass for all applications ~ 1,000 - 1,200 Kg

### Alternative Concepts for Mars Static Lander



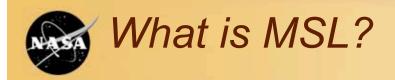
Platform on Legs

- Potential common elements
  - Mechanical platform and skycrane interface.
  - Avionics and telecom.
  - Dynamic testing with skycrane system (qualification).
  - Planetary protection implementation.

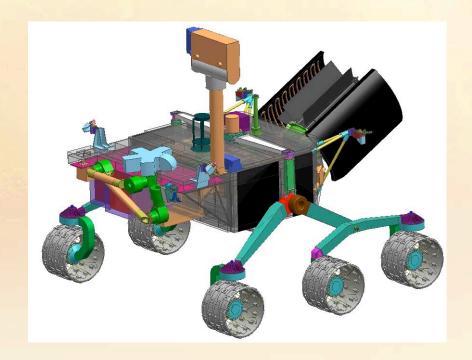


Pallet on Martian Surface





- 600kg
  - 65kg science payload
- 100 watt RTG
- Roving range: 10-20km



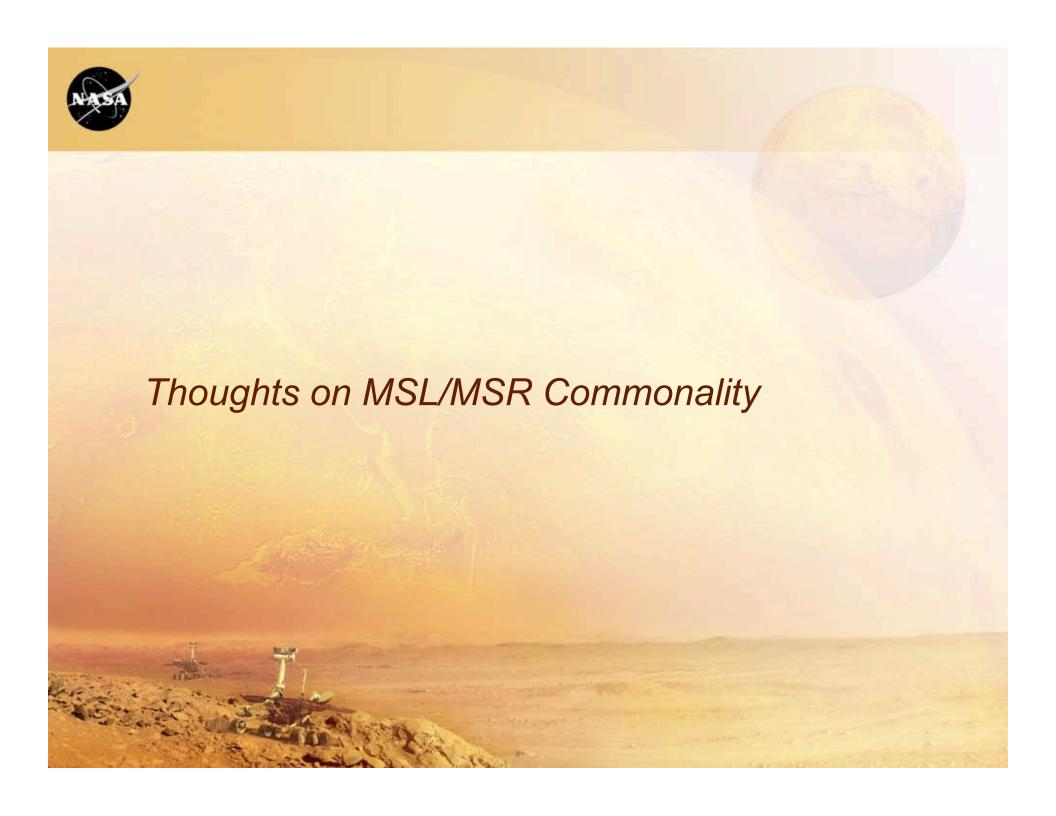


### Repeat Opportunities for MSL-class Rover

- One or two of each of the following
  - MSL in 2009 or 2011
  - AFL mid-next decade
    - Will require more payload capacity (100kg?)
  - Possibly the mobile element of MSR

## Planetary Protection

- MER was Category IV A
- MSL can be Category IV C
- MSR & AFL will likely need to be Category IV B
  - Same as Viking
- How much will planetary protection classification play into design and development of a common rover?
- Additional cost for Category IV B relative to Category IV C will be very significant





## Anatomy of an MSR Mission

- Two identical landers each carrying
  - a platform to land on Mars,
  - a rover to get samples and bring back to the landed platform
  - a bowling ball size container to house the collected samples
  - a Mars Ascent Vehicle (MAV) to launch the sample canister into low Mars orbit
- One orbiter to capture the sample from Mars orbit and deposit into a Earth return vehicle







### Range of MSR Rover Alternatives



Groundbreaking (no rover)

Single Entry Vehicle
Lander, MAV,
Fetch Rover

Dual Entry Vehicles
Lander/MAV &
MSL Reuse

All-Inclusive Rover

Delivered Mass: 1000 kg

Delivered Mass: 1300 kg

Lander/MAV Delivered Mass: 1000 kg Rover Mass 700kg Delivered Mass: 1300 kg



MER Copy

**MER Class** 

Rover Mass: ~200 kg

MSL Reuse

## Why Not Build to Print MER Rover?

- Parts obsolescence will require some changes
  - Cassini ASIC
  - RAD 6K computer
- Design optimized to the Athena payload, and a different payload will require some design changes
  - Design accommodates 5 kg payload mass and 15 kg payload support
  - Arm accommodates 4 instruments at ~ 1.5 kg
  - Mast is fore-optics for Thermal Emission Spectrometer which is contained inside the rover body
- Rover mechanical design is highly integrated extremely brittle given even small changes in "payload" (science, avionics, power, telecom)
  - Volume margin is minimal

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## Highly Optimized for the Volume Available







### Range of MSR Rover Alternatives



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py MER Class

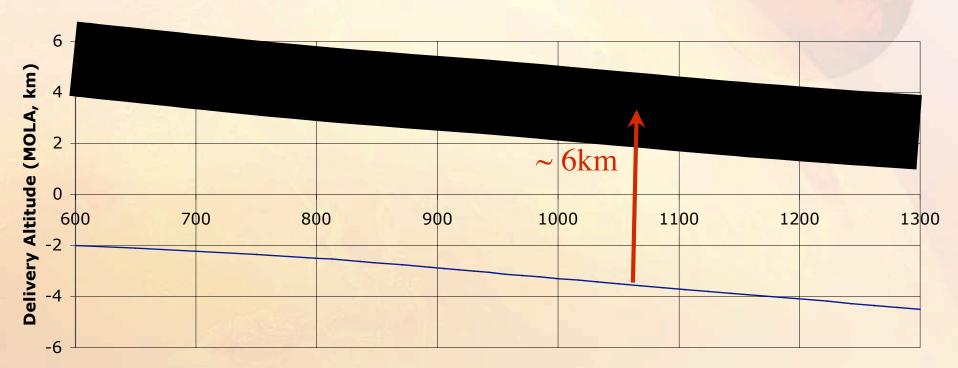
Rover Mass: ~200 kg

MSL Reuse Lander/MAV Delivered Mass: 1000 kg Rover Mass 700kg



### Altitude Capability w/Improved Parachute

#### Improvement due to parachute



#### **Delivered Mass (kg)**

- Common EDL designed for 1300 kg delivery requirement
- Dust degraded performance assumed ( $\tau$  = 3.0)
- 2013 opportunity



### Range of MSR Rover Alternatives



Groundbreaking (no rover)

Single Entry Vehicle
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Dual Entry Vehicles
Lander/MAV &
MSL Reuse

Rover Mass 700kg

Lander/MAV Delivered Delivered Mass: 1000 kg

Delivered Mass: 1300 kg

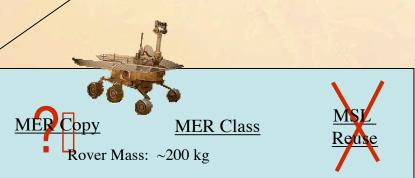
All-Inclusive

Rover

Delivered Mass: 1000 kg

Delivered Mass: 1300 kg

Mass: 1300 kg





### Rover Options

- MER Class (200 kg)
  - Payload mass capability: 20-30 kg
  - Solar powered, lifetime and latitude constrained
  - Substantial non-recurring engineering required
  - Design can be optimized for PP and organic cleanliness issues
- MSL Reuse (600kg)
  - Payload mass capability: 65 kg
  - RTG powered, full latitude and lifetime access
  - NRE limited to payload changes
  - Impact of PP and organic cleanliness requirements is TBD
- All-Inclusive Rover (1,300 kg)
  - Science payload mass capability: 65 kg
  - Capable of carrying MAV & MAV launch equipment
  - RTG powered, full latitude and lifetime access
  - Design can be optimized for PP and organic cleanliness issues



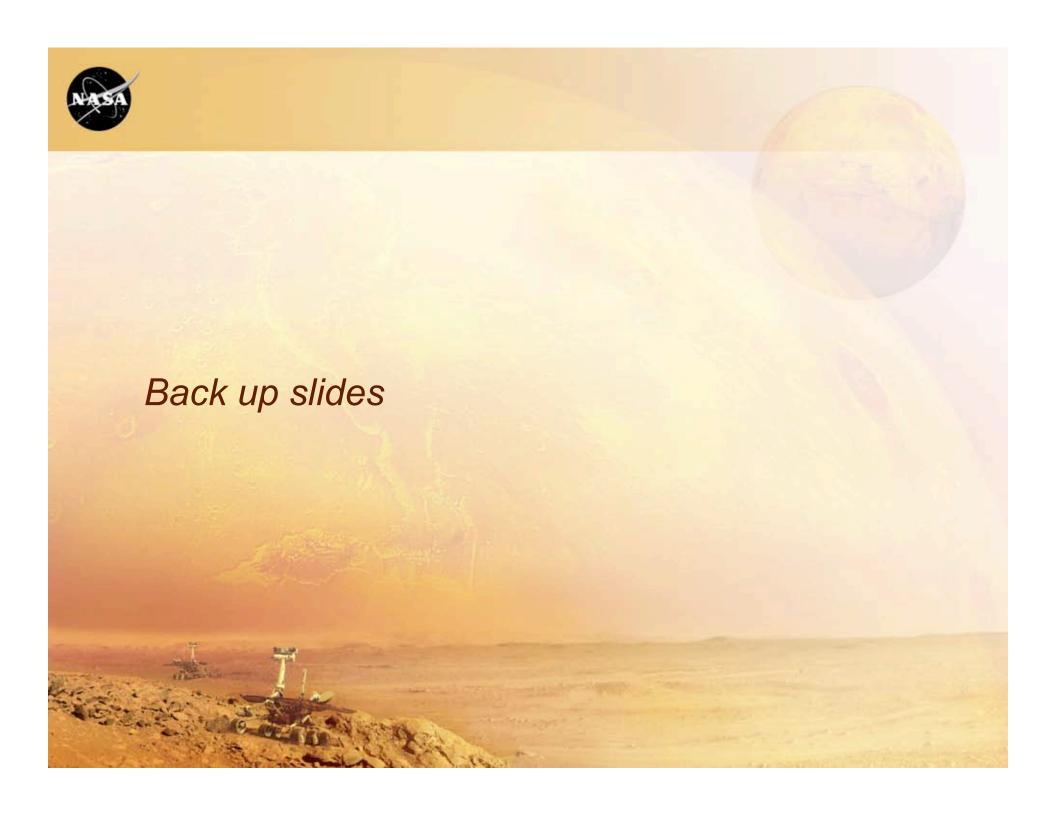
- Orbiter
  - Utilize elements of common orbiter
- Cruise/EDL system
  - Use common EDL system
- Lander
  - Common static lander (possibly same as MHP first flight)
- Mars Ascent Vehicle
  - MSR developed
- Earth Entry Vehicle
  - MSR developed
- Rover
  - Several options

## MSR Conclusions

- Groundbreaking MSR is lowest cost option, but is not acceptable to science
- Reusing MSL rover for MSR requires more costly dual entry vehicle architecture
- Single Entry Fetch Rover and All-Inclusive rover are viable
  - Fetch rover capabilities needs to be assessed by science community
  - Need cost trade between All-Inclusive rover & common lander development
- MSL and all MSR options can make use of common EDL system
  - Commonality benefits depends upon design stability & discipline
  - Common system design will mature through first several flights
  - Near term missions should assume substantial EDL system engineering & validation efforts despite commonality

## Commonality Considerations

- Future Mars robotic missions can make use of common elements
  - EDL
  - Orbiter
  - Lander
- Potential commonality for rovers
  - Commonality between MSL & MSR rovers exists, but might be limited
- Benefits of commonality depend on program architecture and frequency of reuse
- Development of new parachute system critical to future Mars robotic program



## Why Not Reuse MER Airbag EDL Again?

- MER was a ballistic (rather than guided) entry
  - With zero delivery error at entry, landing ellipse major axis ~ 60 70 km, minor axis ~10 km (99%)
    - Expected 2009-2016 approach nav errors of few km (99%) should only increase this by 10 km or so
  - Increase in dust tau associated with dust storms reduces atmospheric density, but also increases atmospheric density uncertainty, which increases landing error ellipse size
- MER EDL altitude capability below –1.3 km MOLA for 2003 atmospheric conditions

## Parachute Development Approach

- Start rapid development program for improved supersonic parachute
  - Complete supersonic qualification in time for MSL '09 launch
    - Likely to be completed ~ 1 year prior to launch
  - Need near-term decision and aggressive start up
- Near term activities include subscale wind tunnel tests to down select parachute technology, development of balloon launch and test article infrastructure, and selection of parachute subcontractor
  - Aim for first development flight test ~ 18 months
  - Provide opportunity for three test/retest opportunities
- Qualify parachute design for subsonic conditions to provide backup for supersonic qualification problems

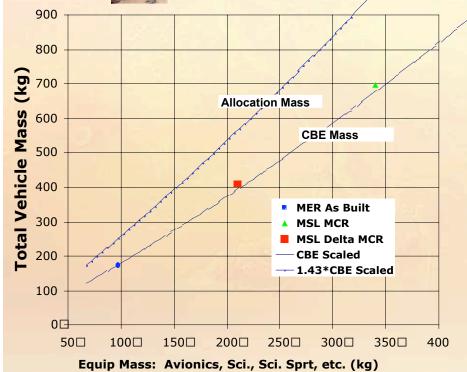


# MER was 180kg why is MSL 600kg?

- MER to MSL Equip Growth (240kg):
  - Power: ~30 kg
  - Thermal ~20 kg
  - Avionics ~10 kg
  - Sci instruments ~40 kg
  - Sci accommodation ~20 kg

#### Sub-total + 120kg

- Structure/mobility "wrap mass" ~ 120kg
- MSL Mass
  - By analogy to MER = 180+240 = 420kg
  - CBE: 410 kg
    - Structure/Mobility: 200 kg CBE
    - Equipment: 210 kg CBE
  - Mass + margin = 410Kg \* 1.43 = 586Kg
  - Project allocation = 600 kg



Analysis of flight Rovers indicates that the mass of the structure and mobility consumes approximately 45%-50% of the total mass